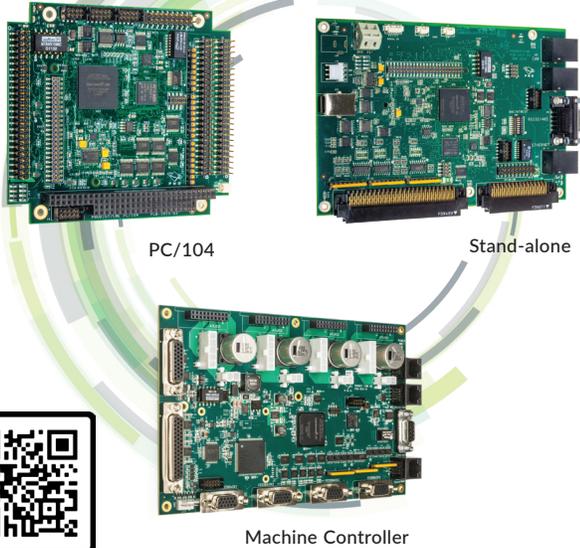


# Prodigy<sup>®</sup> Motion Boards



SCAN ME

**Prodigy<sup>®</sup> Motion Boards** provide high performance board-level motion control for scientific, automation, industrial, and robotic applications. Available in PC/104, standalone, and machine controller configurations, these boards support multiple motor types including Brushless DC, step, and DC Brush motors, and are available in 1, 2, 3, and 4-axis configurations.

### Programmable

CME versions of the board include PMD's C-Motion Engine that allows user application code to run directly on the board, off-loading the system host or enabling stand-alone operation. The Machine controller version has on-board Atlas amplifiers that eliminate the need for external amplifier.

### Powerful and Easy to Use

Based on PMD's industry-leading Magellan<sup>®</sup> Motion Control IC, the Prodigy boards provide user-selectable profile modes including S-curve, trapezoidal, velocity contouring, and electronic gearing with on-the-fly parameter change. Servo loop compensation utilizes a full 32-bit position error, PID with velocity and acceleration feedforward, integration limit and dual biquad filters for sophisticated control of complex loads.

### Built on the Magellan Motion Control IC

The Pro-Motion GUI makes it easy to set-up and analyze system parameters and motion performance. PMD's C-Motion library simplifies the program development process and allows the use of industry standard C/C++ or .NET programming languages.

## FEATURES

- Uses PMD's advanced Magellan<sup>®</sup> Motion Control IC
- PC/104, Stand-alone, and Machine-controller configurations
- Available in 1, 2, 3, and 4-axis configurations
- Supports Brushless DC, step, and DC Brush motors
- S-curve, trapezoidal, electronic gearing, and velocity-contouring
- PC/104 (ISA), Ethernet, CANbus or serial communications
- Advanced PID filter with feedforward and dual biquad filters
- High speed loop rate: 50  $\mu$ sec/axis
- Up to 256 microsteps per full step resolution
- Incremental quadrature and Absolute SSI encoder support
- Includes Pro-Motion<sup>®</sup> and C-Motion<sup>®</sup> development software
- 6-step commutation and field oriented control modes
- High precision 16-bit DAC or PWM amplifier output
- General purpose digital I/O and analog I/O
- Two directional limit switches, plus high speed index, and home inputs per axis

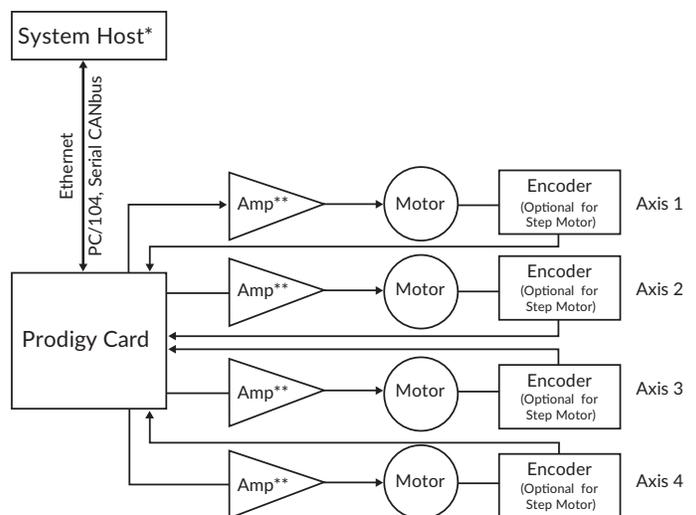
### C-MOTION<sup>®</sup> ENGINE VERSIONS

- Board-level execution of C-Motion code
- Downloaded user application code runs at 96 MIPs
- C-Motion Engine development tools

### MACHINE CONTROLLER VERSION

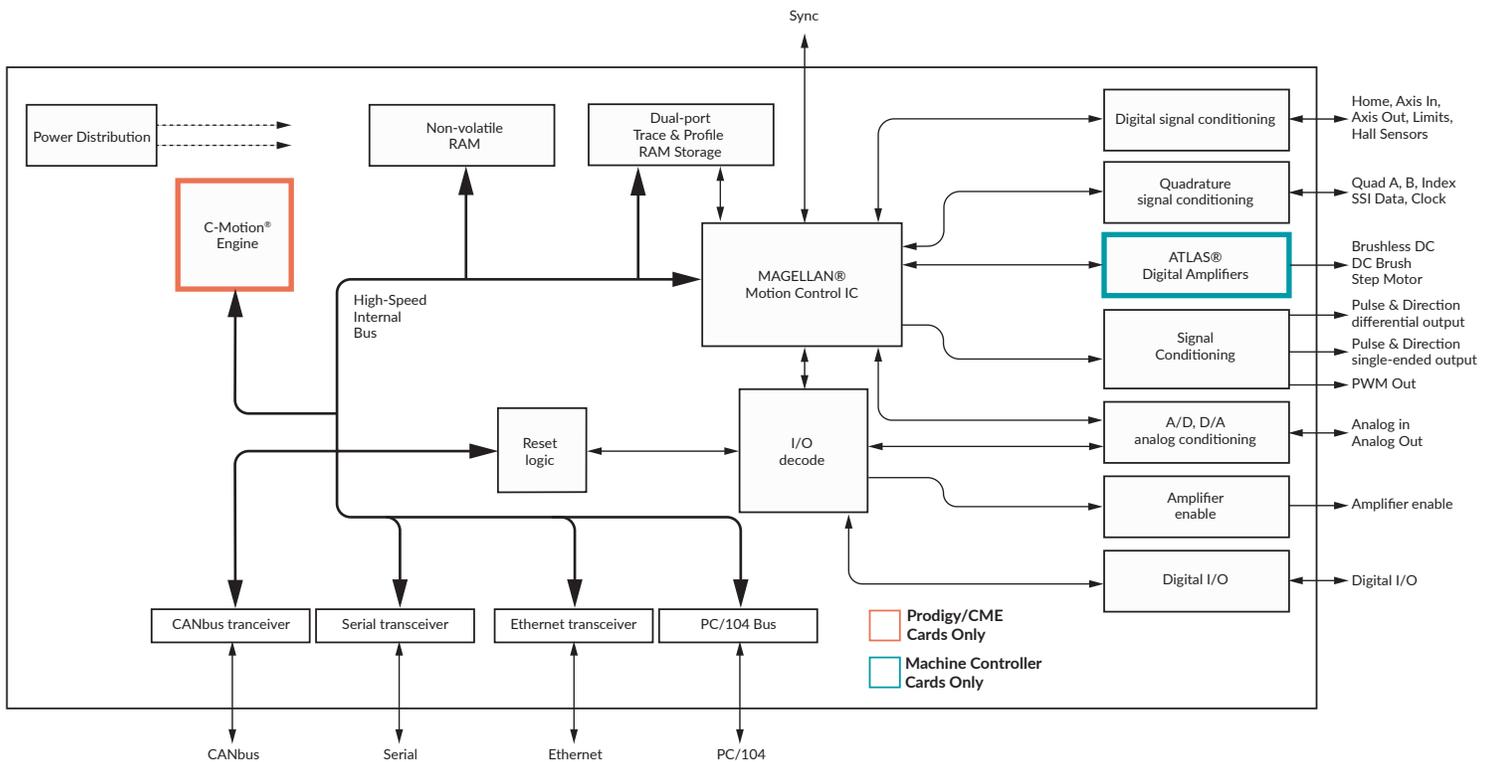
- On-board high performance Atlas amplifiers
- Extensive fault detection including over and undervoltage, motor short, and overtemp
- Up to 1KW peak output power per axis
- Single voltage supply drives motors and board logic

## CONFIGURATION



\*System host optional for Prodigy Programmable PC/104 and Stand-Alone cards  
\*\*External amps used with non-Machine Controller card

# Technical Overview



## SPECIFICATIONS

|   | PC/104  | Stand-alone                                   | Machine Controller  |
|---|---|---|---|
| <b>Configurations</b>                             | Standard or CME   | CME   | CME   |
| <b>Model</b>                                      | PR82 or PR83  | PR13  | PR33  |
| <b>Number of axes supported</b>                   | 1, 2, 3 or 4 axes   |   |   |
| <b>Supported motor types</b>                      | DC Brush, Brushless DC, Step motor  |   |   |
| <b>Servo loop rates</b>                           | 51.2 $\mu$ sec to 1.6 sec. Minimum depends upon number of enabled axes and use of trace |   |   |
| <b>Encoder formats supported</b>                  | quadrature, Absolute SSI  |   |   |
| <b>Quadrature decode rate</b>                     | 8 Mcounts/sec   | 8 Mcounts/sec                                 | 40 Mcounts/sec  |
| <b>Capability for onboard amplifier</b>           | No  | No  | Yes, Atlas Digital Amplifier  |
| <b>Motor output signals</b>                       | Analog $\pm$ 10V, PWM, pulse & direction  | Analog $\pm$ 10V, PWM, pulse & direction      | Analog $\pm$ 10V  |
| <b>General purpose digital I/O</b>                | 8 input, 8 output   | 8 input, 8 output                             | 8 bi-directional, 4 input, 4 output   |
| <b>General purpose analog input</b>               | 8 10-bit channels (0 to 3.3V)   | 8 10-bit channels (0 to 3.3V)                 | 8 16-bit channels (-10V to +10V)  |
| <b>General purpose analog outputs</b>             | N/A   | N/A   | 8 16-bit channels (-10V to +10V)  |
| <b>Limit switches</b>                             | 2 per axis: one for each direction of travel  |   |   |
| <b>CME version user program memory</b>            | 256 KB Flash / 8 KB RAM   |   |   |
| <b>CME version stack memory</b>                   | 8 KB RAM  |   |   |
| <b>Dual ported RAM memory</b>                     | 40KB (standard), 64KB (CME)   | 64KB  | 128K or 468K (enhanced memory option)   |
| <b>Communication modes</b>                        | Standard: PC104 bus, serial, CANbus<br>CME: PC104 bus, serial, CANbus, Ethernet         | serial, CANbus, Ethernet                      | serial, CANbus, Ethernet  |
| <b>On-board amplifier voltage range</b>           | N/A   | N/A   | 12-56V  |
| <b>On-board amplifier max current, continuous</b> | N/A   | N/A   | Brushless DC Motor: 10 Arms,<br>Step motor: 9 Arms,<br>DC Brush Motor: 14 ADC |
| <b>Dimensions</b>                                 | 4.35" x 3.78" x 0.6" (11.1cm x 9.6cm x 1.5cm)   | 6.30" x 4.23" x .8" (16.0cm x 10.7cm x 2.0cm) | 7.80" x 4.88" x .78" (19.8cm x 12.4cm x 1.98cm)                               |

# Development Tools

## 1 EASY START-UP Developers Kit

### INCLUDES

- Prodigy Developer Kits
- Pro-Motion software
- Software Development Kit (SDK) with C-Motion
- Complete manual set
- Complete cable and prototyping connector set

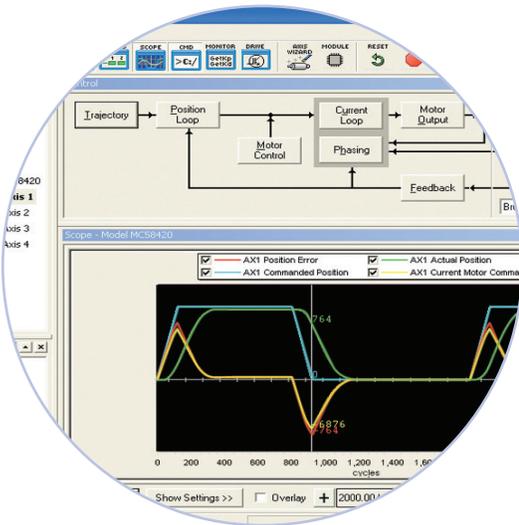


## 2 TUNE & OPTIMIZE Pro-Motion GUI®

Pro-Motion is a sophisticated, easy-to-use Windows-based exerciser program for use with PMD motion control ICs, modules, and boards.

### FEATURES

- Motion oscilloscope graphically displays processor parameters in real-time
- Autotuning
- Ability to save and load settings
- Axis wizard
- Distance and time units conversion
- Motor-specific parameter setup
- Axis shuttle performs programmable motion between two positions
- Communications monitor echoes all commands sent by Pro-Motion to the board
- Advanced Bode analysis for frequency machine response



## 3 BUILD THE APP C-Motion®

C-Motion is a complete, easy-to-use, motion programming language that includes a source library containing all the code required for communicating with PMD motion ICs, board, and modules.

### C-MOTION FEATURES INCLUDE:

- Extensive library of commands for virtually all motion design needs
- Develop embeddable C/C++ applications
- Complete, functional examples
- Supports PC/104, serial, CAN, Ethernet, and SPI communications

```
code for executing a profile and trace
captured in this example could be used for tuning the Pro
trace buffer wrap mode to a one time trace
TraceMode(hAxis1, PMDTraceOneTime);

set the processor variables that we want to capture
SetTraceVariable(hAxis1, PMDTraceVariable1, PMDAxis1,
SetTraceVariable(hAxis1, PMDTraceVariable2, PMDAxis1,
SetTraceVariable(hAxis1, PMDTraceVariable3, PMDAxis1, P

// set the trace to begin when we issue the next update command
SetTraceStart(hAxis1, PMDTraceConditionNextUpdate);

// set the trace to stop when the MotionComplete event occurs
SetTraceStop(hAxis1, PMDTraceConditionEventStatus,
PMDEventMotionCompleteBit, PMDTraceStateHigh);
SetProfileMode(hAxis1, PMDTrapezoidalProfile);

set the profile parameters
SetPosition(hAxis1, 200000);
SetVelocity(hAxis1, 0x200000);
SetAcceleration(hAxis1, 0x1000);
SetDeceleration(hAxis1, 0x1000);

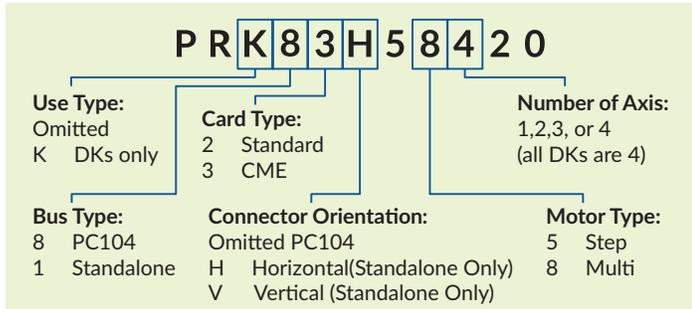
tion
;
;
```

# PMD PRODUCT FAMILY OVERVIEW

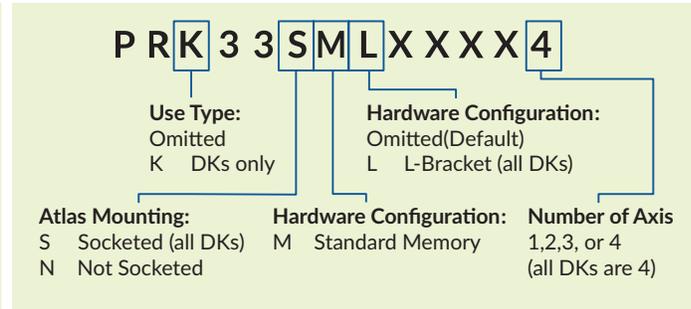
|   | # Axes  | Motor Types  | Format   | Voltage   | Communication   | Features   |
|---|---------|--|--|---|---|--|
| <b>JUNO® VELOCITY &amp; TORQUE CONTROL ICs</b><br> | 1       | <ul style="list-style-type: none"> <li>Brushless DC</li> <li>DC Brush</li> <li>Step Motor</li> </ul> | <ul style="list-style-type: none"> <li>64-pin TQFP</li> <li>56-pin VQFN</li> </ul>                       | 3.3 V   | <ul style="list-style-type: none"> <li>RS232/485</li> <li>CANbus</li> <li>SPI</li> </ul>                          | <ul style="list-style-type: none"> <li>Velocity control</li> <li>Current control</li> <li>Field oriented control</li> </ul>  |
| <b>MAGELLAN® MOTION CONTROL ICs</b><br>            | 1,2,3,4 | <ul style="list-style-type: none"> <li>Brushless DC</li> <li>DC Brush</li> <li>Step Motor</li> </ul> | <ul style="list-style-type: none"> <li>144-pin TQFP</li> <li>100-pin TQF</li> </ul>                      | 3.3 V   | <ul style="list-style-type: none"> <li>RS232/485</li> <li>CANbus</li> <li>SPI</li> <li>Parallel</li> </ul>        | <ul style="list-style-type: none"> <li>Position control</li> <li>Torque/current control</li> <li>Field oriented control</li> <li>Profile generation</li> </ul>   |
| <b>ATLAS® DIGITAL AMPLIFIERS</b><br>               | 1       | <ul style="list-style-type: none"> <li>Brushless DC</li> <li>DC Brush</li> <li>Step Motor</li> </ul> | <ul style="list-style-type: none"> <li>20-pin solderable module</li> </ul>                               | 12-56 V   | <ul style="list-style-type: none"> <li>SPI</li> <li>Pulse and direction</li> </ul>                                | <ul style="list-style-type: none"> <li>Torque/current control</li> <li>Field oriented control</li> <li>MOSFET amplifier</li> </ul>   |
| <b>ION®/CME N-SERIES DIGITAL DRIVES</b><br>        | 1       | <ul style="list-style-type: none"> <li>Brushless DC</li> <li>DC Brush</li> <li>Step Motor</li> </ul> | <ul style="list-style-type: none"> <li>Fully enclosed PCB-mounted module</li> </ul>                      | 12-56 V   | <ul style="list-style-type: none"> <li>Ethernet</li> <li>RS232/485</li> <li>CAN FD</li> <li>SPI</li> </ul>        | <ul style="list-style-type: none"> <li>Position control</li> <li>Torque/current control</li> <li>Field oriented control</li> <li>Profile generation</li> <li>MOSFET amplifier</li> <li>Downloadable user code</li> </ul> |
| <b>ION® 500 &amp; 3000 DIGITAL DRIVES</b><br>     | 1       | <ul style="list-style-type: none"> <li>Brushless DC</li> <li>DC Brush</li> <li>Step Motor</li> </ul> | <ul style="list-style-type: none"> <li>Fully enclosed cable-connected module</li> </ul>                  | 12-56 V<br>20-195 V   | <ul style="list-style-type: none"> <li>Ethernet</li> <li>RS232/485</li> <li>CANbus</li> </ul>                     | <ul style="list-style-type: none"> <li>Position control</li> <li>Torque/current control</li> <li>Field oriented control</li> <li>Profile generation</li> <li>MOSFET amplifier</li> <li>Downloadable user code</li> </ul> |
| <b>PRODIGY® MOTION BOARDS</b><br>                | 1,2,3,4 | <ul style="list-style-type: none"> <li>Brushless DC</li> <li>DC Brush</li> <li>Step Motor</li> </ul> | <ul style="list-style-type: none"> <li>Machine Controller</li> <li>PC/104</li> <li>Standalone</li> </ul> | <ul style="list-style-type: none"> <li>5 V: PC/104 and Standalone</li> <li>12-56 V: Machine Controller</li> </ul> | <ul style="list-style-type: none"> <li>Ethernet</li> <li>RS232/485</li> <li>CANbus</li> <li>PC/104 bus</li> </ul> | <ul style="list-style-type: none"> <li>Position control</li> <li>Torque/current control</li> <li>Field oriented control</li> <li>Profile generation</li> <li>Downloadable user code</li> </ul>                           |

C-Motion® is the common motion language for all Performance Motion Devices products.

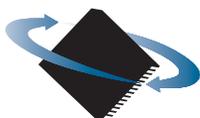
## FOR ORDERING PC/104 OR STANDALONE VERSIONS



## FOR ORDERING MACHINE CONTROLLER VERSIONS



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**PERFORMANCE  
MOTION DEVICES**  
MOTION CONTROL AT ITS CORE

### About Performance Motion Devices

Performance Motion Devices (PMD) is a worldwide leader in motion control ICs, boards and modules. Dedicated to providing cost-effective, high performance motion systems to OEM customers, PMD utilizes extensive in-house expertise to minimize time-to-market and maximize customer satisfaction.

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